

Last time:  $V$  finite dim./ $k$ ,  $B$  non-degenerate symmetric bilinear form  $\Rightarrow$

$\exists$  orthogonal basis  $(e_1, \dots, e_n)$ ,  $B(e_i, e_j) = 0 \ \forall i \neq j$

+ over  $\mathbb{C}$ , can ensure  $B(e_i, e_i) = 1$   
 $\mathbb{R}$   $B(e_i, e_i) = \pm 1$

\* What about the skew-symmetric case? (suppose  $\text{char}(k) \neq 2$ )

We can still find a "standard basis" for  $V$  finite dim. vect. space with  
 $B: V \times V \rightarrow k$  non-degenerate skew-symmetric bilinear form (a.k.a: symplectic form)

but the process is slightly different since  $B(v, v) = 0 \ \forall v \in V$ .

Instead: pick any nonzero  $e_1 \in V$ ; since  $B$  is non-degenerate,  $B(e_1, \cdot): V \rightarrow k$   
 is nonzero  $\Rightarrow \exists f_1 \in V$  st.  $B(e_1, f_1) \neq 0$ , can make it = 1 by scaling  $f_1$ .

Now we find  $\text{span}(e_1, f_1) \cap \text{span}(e_1, f_1)^\perp = \{0\}$  (if  $v = ae_1 + bf_1$ , has  
 so  $V = \text{span}(e_1, f_1) \oplus \text{span}(e_1, f_1)^\perp$ ,  $B(v, e_1) = B(v, f_1) = 0 \Rightarrow a = b = 0$ )

and study the restriction of  $B$  to the latter subspace (induction on dim.).

$\Rightarrow$  Prop:  $\left\{ \begin{array}{l} V \text{ finite dim! over } k, \text{ char}(k) \neq 2, \\ B \text{ nondegenerate skewsymmetric bilinear form } V \times V \rightarrow k \\ \Rightarrow \text{dim } V \text{ is even, and } V \text{ has a basis } (e_1, f_1, \dots, e_n, f_n) \text{ st.} \\ B(e_i, e_j) = B(f_i, f_j) = 0, \quad B(e_i, f_j) = \delta_{ij} = -B(f_j, e_i). \end{array} \right.$

ie. matrix of  $B$  is  $\left( \begin{array}{cc|cc} 0 & 1 & & \\ -1 & 0 & & \\ \hline & & 0 & 1 \\ & & -1 & 0 \\ & & & \ddots \end{array} \right)$

The group of linear transformations preserving  $B$  is called the symplectic group  
 $\text{Sp}(V, B) \cong \text{Sp}(2n, k)$ .

Tensors and multilinear algebra - see handout.

$V, W$  finite dimensional vector spaces over  $k \Rightarrow$  the tensor product is a  
 vector space  $V \otimes W$  + a bilinear map  $V \times W \rightarrow V \otimes W$ .

$$(v, w) \mapsto v \otimes w$$

Three definitions (from concrete to abstract; all are equivalent ie. give same  
 output up to natural isomorphism)

- Def. 1: Choose bases  $e_1, \dots, e_m$  of  $V$ ,  $f_1, \dots, f_n$  of  $W$ . Then  $V \otimes W$  is the vector space with basis  $\{e_i \otimes f_j, 1 \leq i \leq m, 1 \leq j \leq n\}$ . ②

The bilinear map is  $(e_i, f_j) \mapsto e_i \otimes f_j$  + extend by linearity.

Elements of the form  $v \otimes w = (\sum a_i e_i) \otimes (\sum b_j f_j) = \sum a_i b_j (e_i \otimes f_j)$  are called pure tensors; not every element of  $V \otimes W$  is of this form!

The rank of an element of  $V \otimes W$  = minimal number of terms needed to express it as a linear combination of pure tensors.

This is concrete & makes it clear that  $\dim(V \otimes W) = mn$ , but the independence of the choice of basis isn't obvious. To de-emphasize the basis:

- Def. 2: Start with a vector space  $U$  with basis  $\{v \otimes w \mid v \in V, w \in W\}$ . (This is insanely large: usually this basis is uncountable!), and quotient it by a subspace  $R$  of relations among these elements:

$$R \subset U = \text{the span of } \begin{aligned} &(\lambda v) \otimes w - \lambda(v \otimes w) \quad \forall \lambda, v, w \\ &v \otimes (\lambda w) - \lambda(v \otimes w) \\ &(u+v) \otimes w - u \otimes w - v \otimes w \quad \forall u, v, w. \\ &u \otimes (v+w) - u \otimes v - u \otimes w \end{aligned}$$

Defining  $V \otimes W = U/R$  sets all these to zero, enforcing bilinearity of the map  $(v, w) \mapsto v \otimes w$ .

This shows independence on the basis, but involves an unpleasantly large construction (at the end, if we have bases  $\{e_i\}$  of  $V$ ,  $\{f_j\}$  of  $W$ , the relations in  $R$  do show all elements of  $V \otimes W$  are linear combinations of  $e_i \otimes f_j$ , but before one checks this it's not even obvious that  $\dim(V \otimes W) < \infty$ )

- The least concrete, yet most mathematically satisfactory definition, characterizes what  $V \otimes W$  does without spelling out how it's actually constructed: namely, that  $V \otimes W$  is the largest space we can build s.t. a linear map from  $V \otimes W$  to another space, when evaluated on pure tensors  $v \otimes w$ , is bilinear in  $v$  and  $w$ . (eg. in Def. 2:  $U$  is too big, quotient by  $R$  enforces bilinearity)

Def. 3: The tensor product  $V \otimes W$  is the universal vector space through which all bilinear maps from  $V \times W$  factor, i.e. it is a vector space  $V \otimes W$  + a bilinear map  $\beta: V \times W \rightarrow V \otimes W$  such that, given any vector space  $U$  over  $k$ , and any bilinear map  $b: V \times W \rightarrow U$ , there exists a unique linear map  $\varphi: V \otimes W \rightarrow U$  st.  $b = \varphi \circ \beta$



This is in general a rank 2 tensor, except if  $ad-bc=0$ , then can write it as a pure tensor  $(xe_1^* + ye_2^*) \otimes (zf_1 + wf_2)$

(4)

Fact:  $\|$  Tensor rank in  $V^* \otimes W$  is the same as rank in  $\text{Hom}(V, W)$ !  
(hence the name).

(Rank 1 case:  $l \otimes w$  corresponds to  $(v \mapsto l(v)w)$  whose image =  $\text{span}(w)$ !)

Easiest to see if take basis of  $V$  in which  $e_{r+1}, \dots, e_n$  basis of  $\ker \varphi$  and of  $W$  in which  $f_1, \dots, f_r$  basis of  $\text{Im } \varphi$ , with  $f_i = \varphi(e_i) \forall 1 \leq i \leq r$ .

Then  $\varphi$  corresponds to  $\sum_{i=1}^r e_i^* \otimes f_i$ .  $(\Leftrightarrow M(\varphi) = \left( \begin{array}{c|c} 1 & 0 \\ \hline 0 & 0 \end{array} \right))$   
 $\xleftrightarrow{r = \text{rank } \varphi}$

The isomorphism  $\text{Hom}(V, W) \cong V^* \otimes W$  also implies:

- $(V \otimes W)^* \cong V^* \otimes W^*$ . Can view this as:

$$\begin{aligned} (V \otimes W)^* &= \text{Hom}(V \otimes W, k) = \{ \text{Bilinear maps } V \times W \rightarrow k \} \\ &\cong \text{Hom}(V, W^*) \quad (\text{via } b \mapsto \varphi_b: v \mapsto b(v, \cdot)) \\ &\cong V^* \otimes W^* \end{aligned}$$

- $\text{Hom}(V, W) \cong V^* \otimes W \cong (W^*)^* \otimes V^* \cong \text{Hom}(W^*, V^*)$

This is actually the transpose construction  $\varphi \in \text{Hom}(V, W) \mapsto \varphi^t: W^* \rightarrow V^*$ .

(easiest to check on rank 1  $\varphi(v) = l(v)w \Leftrightarrow \varphi^t(\alpha) = \alpha \circ \varphi = \alpha(w)l = \text{ev}_w(\alpha)l$ )  
 $l \otimes w \Leftrightarrow \text{ev}_w \circ l$ .

- We can now properly define the trace of a linear operator!

In "ordinary" linear algebra classes, one defines the trace of an  $n \times n$  matrix

$A = (a_{ij})$  to be  $\text{tr}(A) = \sum_{i=1}^n a_{ii}$  sum of diagonal entries, then noting that

$\text{tr}(AB) = \sum_{ij} a_{ij} b_{ji} = \text{tr}(BA)$  we have  $\text{tr}(P^{-1}AP) = \text{tr}(A)$  and so

the trace of  $T: V \rightarrow V$  is defined to be the trace of  $M(T)$  in any basis.

We could also try to define the trace via eigenvalues and their multiplicities,

over an alg. closed field: in a basis where  $M(T)$  is triangular it is

manifest that  $\text{tr}(T) = \sum n_i \lambda_i$

- We can do better (conceptually), by using  $\text{Hom}(V, V) \cong V^* \otimes V$ , and

the contraction linear map  $V^* \otimes V \rightarrow k$ . Namely, there's a natural

bilinear pairing  $\ell: V^* \times V \rightarrow k$  and it determines  $\text{tr}: V^* \otimes V \rightarrow k$   
 $(\ell, v) \mapsto \ell(v)$  on pure tensors,  $\ell \otimes v \mapsto \ell(v)$

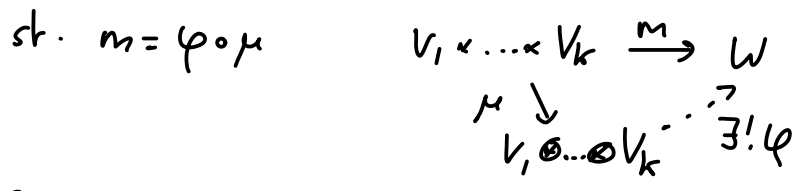
This is indeed equivalent to the usual def<sup>n</sup>: choosing a basis  $(e_i)$  and the dual basis  $(e_i^*)$ ,  $\text{tr}(e_i^* \otimes e_j) = e_i^*(e_j) = \delta_{ij} \iff$  trace of the matrix with single entry 1 in pos.  $(j, i)$ .

Def. || A map  $m: V_1 \times \dots \times V_k \rightarrow W$  is multilinear if it is linear in each variable separately.

The tensor product  $V_1 \otimes \dots \otimes V_k$  can be defined as above, either using bases of  $V_1 \dots V_k$ , or as a quotient of a universal vector space by relations, or via universal property for multilinear maps:

There is a multilinear map  $\mu: V_1 \times \dots \times V_k \rightarrow V_1 \otimes \dots \otimes V_k$  st.  
 $(v_1, \dots, v_k) \mapsto v_1 \otimes \dots \otimes v_k$

$\forall W$  vector space,  $\forall m: V_1 \times \dots \times V_k \rightarrow W$  multilinear,  $\exists! \varphi \in \text{Hom}(V_1 \otimes \dots \otimes V_k, W)$



In fact nothing new is happening, because  $(U \otimes V) \otimes W = U \otimes (V \otimes W) = U \otimes V \otimes W$ .

But... in the special case of  $\underbrace{V \otimes \dots \otimes V}_{n \text{ times}} = V^{\otimes n}$  (by convention  $V^{\otimes 0} = k$ ,  $V^{\otimes 1} = V$ )

we have bilinear maps  $V^{\otimes k} \times V^{\otimes l} \rightarrow V^{\otimes (k+l)} \quad \forall k, l \geq 0$ , which taken together define a multiplication on the tensor algebra  $T(V) = \bigoplus_{n=0}^{\infty} V^{\otimes n}$  making it a noncommutative ring.