

## EECS 336: Lecture 6: Introduction to Algorithms

### Dynamic Programming (cont) interval pricing

Reading: 6.5

#### Last Time:

- Approach: isolating previous decisions
- Shortest-paths (Bellman-Ford Alg)

#### Today:

- interval pricing
- summary of dynamic programming
- comparison to divide and conquer

### Example: Interval Pricing

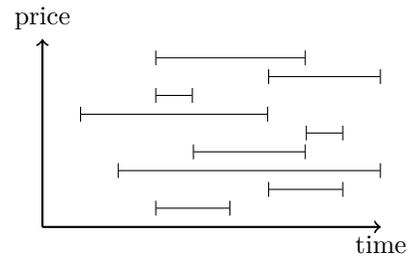
#### input:

- $n$  customers  $S = \{1, \dots, n\}$
- $T$  days.
- $i$ 's ok days:  $I_i = \{s_i, \dots, f_i\}$
- $i$ 's value:  $v_i \in \{1, \dots, V\}$

#### output:

- prices  $p[t]$  for day  $t$ .
- consumer  $i$  buys on day  $t_i = \operatorname{argmin}_{t \in I_i} p[t]$  if  $p[t] \leq v_i$ .
- revenue =  $\sum_{i \text{ that buys}} p[t_i]$ .
- goal: maximize revenue.

#### Example:

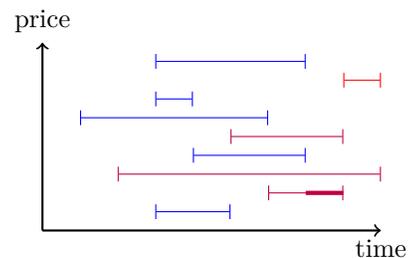


let's use dynamic programming. subproblem?

**Question:** What is "first decision we can make" to separate into subproblems?

**Answer:** day and price of smallest price.

#### Example:



**Step I: identify subproblem in English**

$OPT(s, f, p)$  = "optimal revenue from customers  $i$  with intervals  $\{s_i, \dots, f_i\}$  contained within interval  $\{s + 1, \dots, f - 1\}$  with minimum price at least  $p$ ."

**Note:** can be improved to  $O(n^4)$  with slightly better program.

**Step VII: implementation**

(exercise)

**Step II: write recurrence**

$$\begin{aligned}
 &OPT(s, f, p) \\
 &= \max_{t \in \{s+1, \dots, f-1\}; q \in \{p, \dots, V\}} \text{Rev}(s, t, f, p) \\
 &\quad + OPT(s, t, q) \\
 &\quad + OPT(t, f, q).
 \end{aligned}$$

with

$\text{Rev}(s, t, f, p)$  = "the revenue from customers  $i$  with intervals  $\{s_i, \dots, f_i\}$  contained within interval  $\{s + 1, \dots, f - 1\}$  with price  $p$ ."

**Step III: value of optimal solution**

- optimal interval pricing =  $OPT(0, T + 1, 0)$

**Step IV: base case**

- $OPT(s, s + 1, p) = 0$ .
- $OPT(s, t, V + 1) = 0$ .

**Step V: iterative DP**

(exercise)

**Correctness**

induction

**Step VI: Runtime**

- precompute  $\text{Rev}(s, t, f, p)$  in  $O(T^3 V n)$  time.
- size of table:  $O(T^2 V)$
- cost of combine:  $O(TV)$
- total:  $O(T^3 V(V + n))$

**Note:** without loss of generality  $T, V$  are  $O(n)$  so runtime is  $O(n^5)$ .

## Summary of Dynamic Programming

“divide the problem into small number of subproblems and memoize solution to avoid redundant computation.”

### Finding Subproblems

- identify a first decision, subproblems for each outcome of decision.
- partition problem, summarize information from one part needed to solve other part.

### Subproblem Properties

1. succinct (only a polynomial number of them)
2. efficiently combinable.
3. depend on “smaller” subproblems (avoid infinite loops), e.g.,
  - process elements “once and for all” [today]
  - “measure of progress/size” [coming soon]

### Runtime Analysis

runtime = initialization + size of table  $\times$  cost to combine

### Finding Solution

- write DP to identify value of optimal solution.
- traverse memoization table to determine actual solution.